



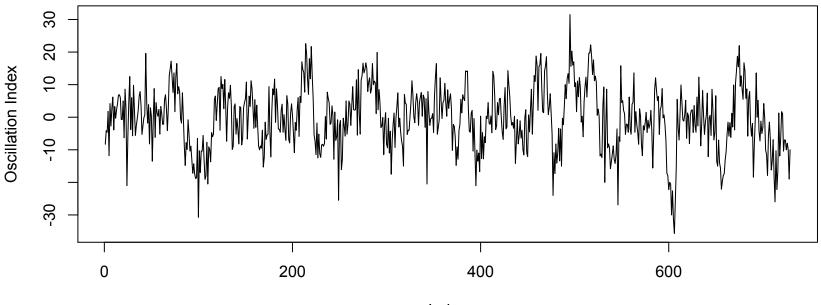
Time Series Analysis

7th of February 2023

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Example: Monthly Southern Oscillation Index

Monthly difference in sea-surface air pressure between Darwin and Tahiti



Index

Used for predicting rainfall in parts of Australia

A time series is a process in which a given observation depends on other datapoints in the same series.

Linear regression models:

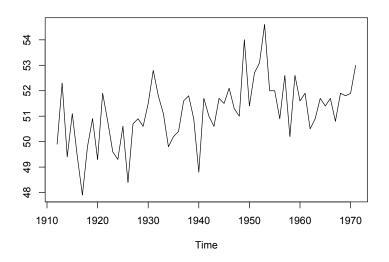
- Response variable (y)
- Independent variables (x)

Time series:

• Single process (y)



- Exploit correlations within the data in order to understand and model the data
- Potentially forecast likelihood of future events



When analysing time series, we are interested in how two values in the series – separated by k time-steps – affect each other.

kth autocovariance:

$$\gamma_k = E(y_t - \mu)(y_{t-k} - \mu)$$
 K: Lag

Average covariance between pairs of values that are k time steps apart in the series.

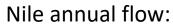
Since these are dependent on the scale of the process, these need to be standardised:

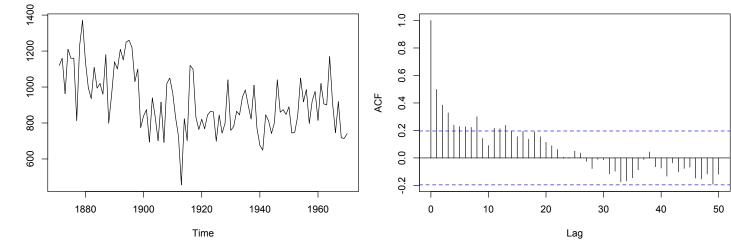
kth autocorrelation:

$$\rho_k = \frac{\gamma_k}{\gamma_0}$$

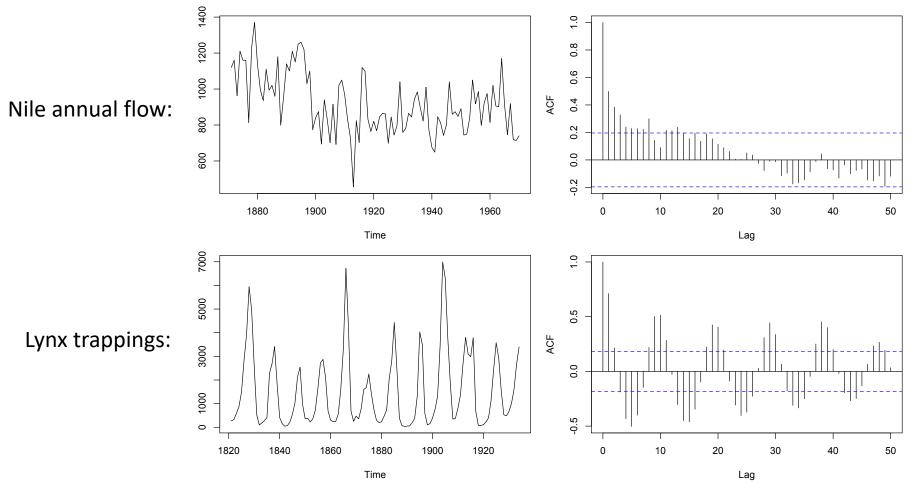
The autocorrelation function is useful for characterising time series.

Autocorrelation function:





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Autoregressive (AR) time series models:

AR(1):
$$y_t = c + \varphi_1 y_{t-1} + \varepsilon_t$$

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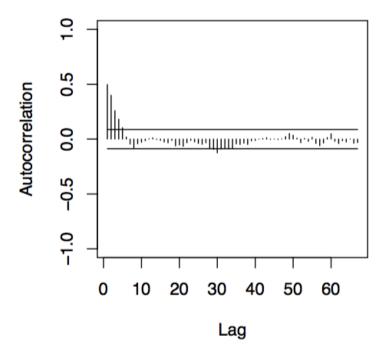
AR(p):
$$y_t = c + \varphi_1 y_{t-1} + \dots + \varphi_p y_{t-p} + \varepsilon_t$$

Similarities to multiple regression model, except for the dependencies Parameters estimated using least squares or maximum likelihood

Assumptions:

- Independent Gaussian errors
- Covariance stationary process (trend doesn't change over time)

Autoregressive (AR) time series models:



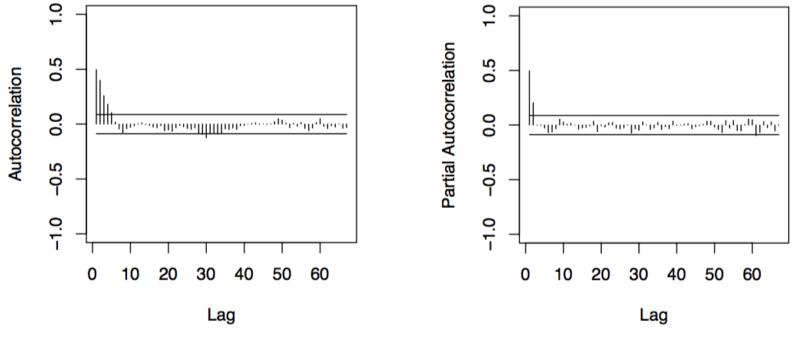
How to interpret ACF?

- Positive parameters: ACF should decay, not oscillate.
- Should decay gradually until within the confidence interval, then stay there.
- Can't infer order...

AR(2) with c=0, ϕ_1 =0.4 and ϕ_2 =0.2

Autoregressive (AR) time series models:

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Partial autocorrelation function: $\alpha(p) = \phi_p$ from a AR(p) model

Parsimonious modelling:

- First try AR(1), then AR(2), etc. until $H_0: \alpha(p) = 0$ is not rejected.
- Failure to reject leads us to conclude that AR(p) is more appropriate than AR(p-1).

Moving Average (MA) time series models:

MA(1):
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Moving Average (MA) time series models:

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- MA(2): $y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2}$
- MA(q): $y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}$

Unlike multiple regression model there are multiple error terms However, the current state is only ever dependent on a known no. of previous states

Since the current state only depends on the previous q states, the ACF should suddenly drop to zero, unlike AR(p) processes

More general models:

Auto Regressive, Moving Average:

ARMA(p,q):
$$y_t = c + \varphi_1 y_{t-1} + \dots + \varphi_p y_{t-p} + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}$$

AR(p) MA(q)

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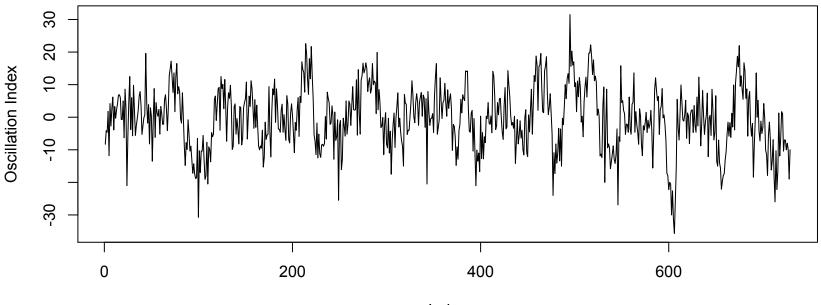
ARIMA(p,1,q): $x_t = y_t - y_{t-1}$ then model as ARMA(p,q)

ARIMA(p,d,q): $x_t = \nabla^d y_t$ take dth order differences

Considering ARIMA models can be a useful "transformation" if assumptions are violated

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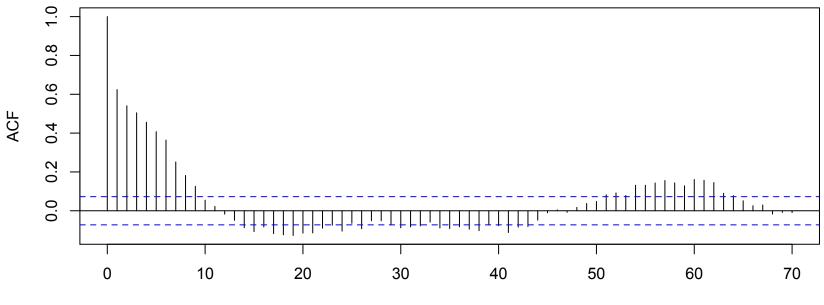


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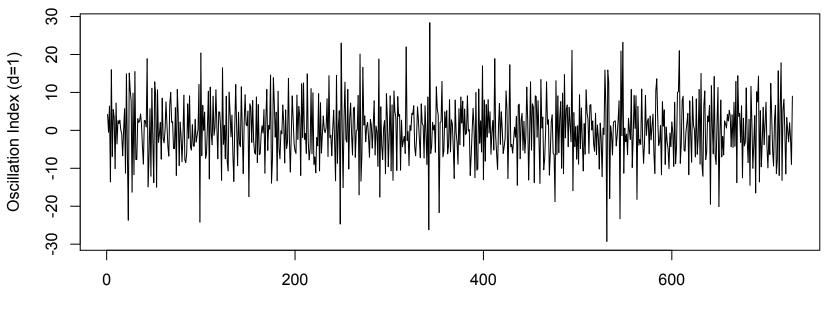
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Lag

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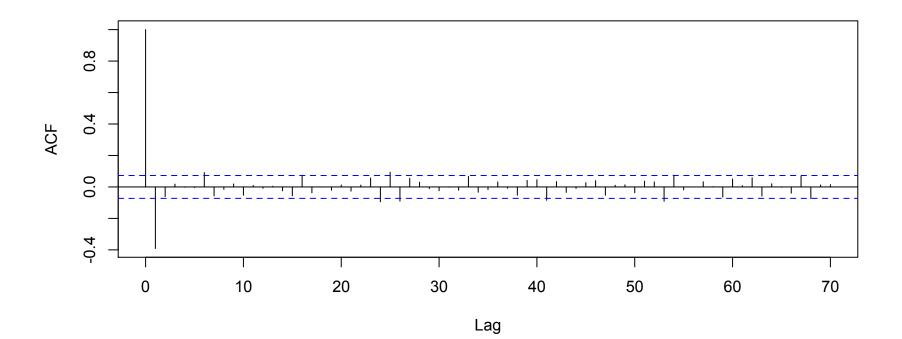
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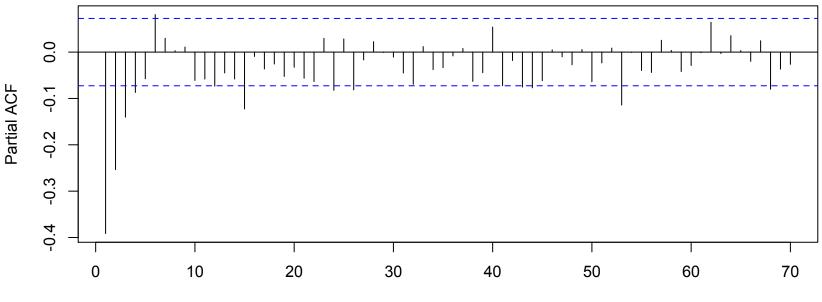
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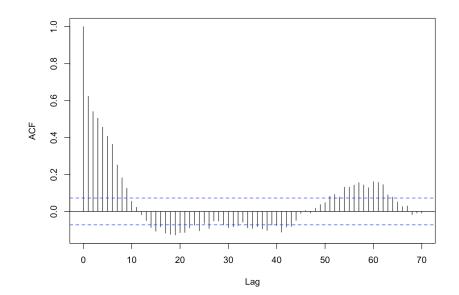
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Try ARIMA(0,1,1) model:

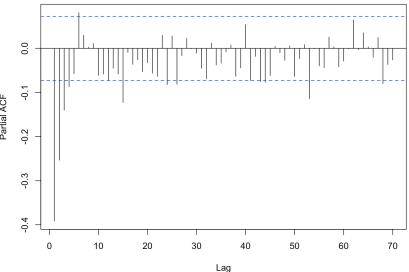
R functions:

acf(x,lag.max=70)



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acf(x,lag.max=70) diff(x) pacf(diff(x),lag.max=70)



R functions:

acf(x,lag.max=70)

diff(x)

pacf(diff(x),lag.max=70)

arima(x,order=c(0,1,1))

```
##
## Call:
## arima(x = x$Index, order = c(0, 1, 1))
##
## Coefficients:
## ma1
## -0.5579
## s.e. 0.0308
##
## sigma^2 estimated as 52.94: log likelihood
= -2477.98, aic = 4959.96
```